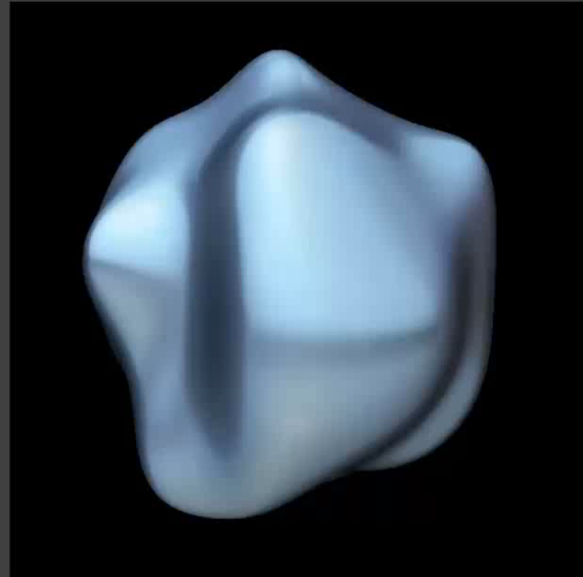


Surface ST vs Image ST



CG rendering

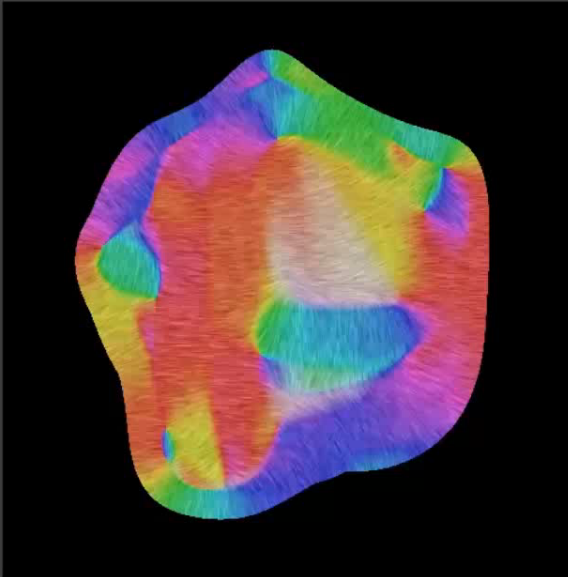
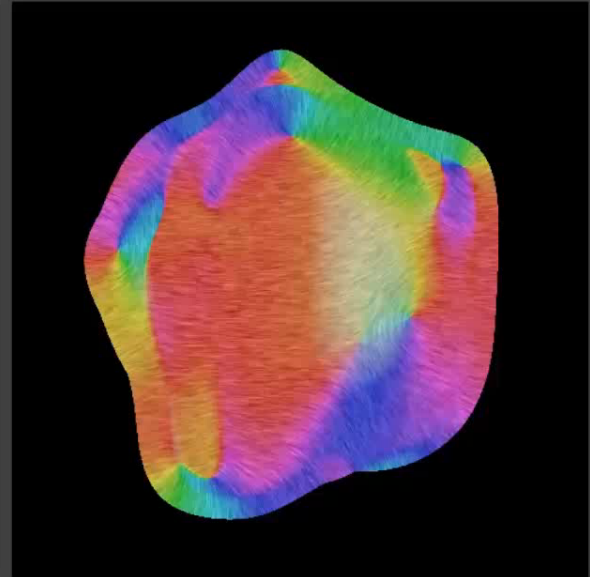


Image based ST



Surface based ST

Shape ST vs Image ST



CG rendering

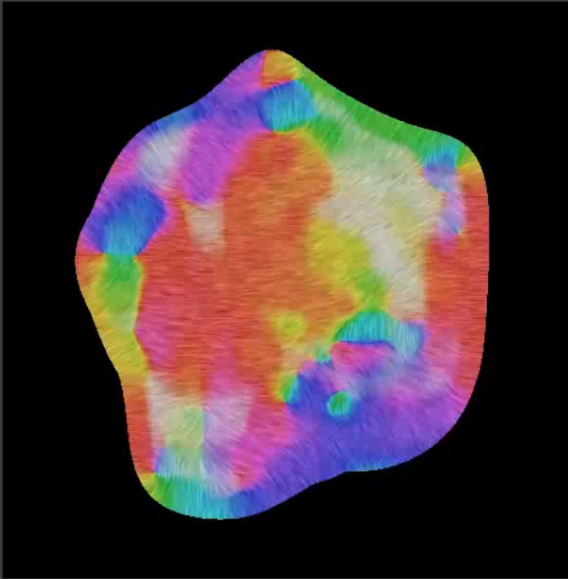
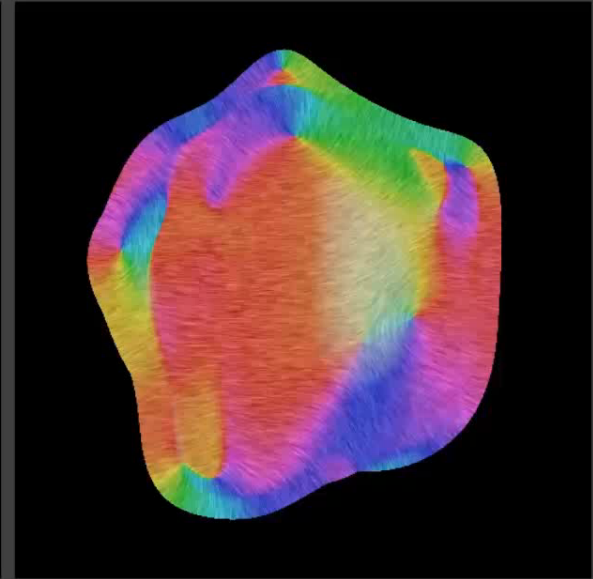
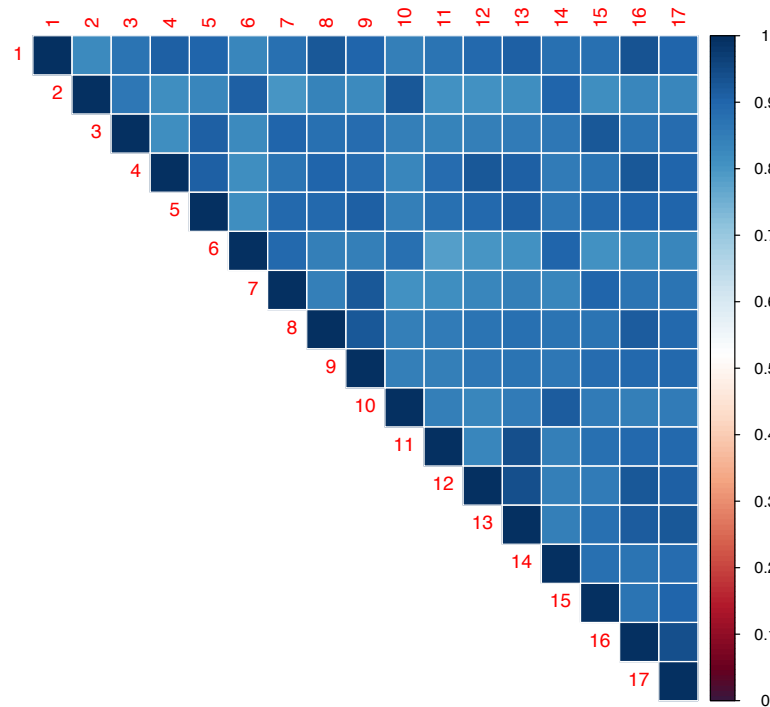


Image based ST

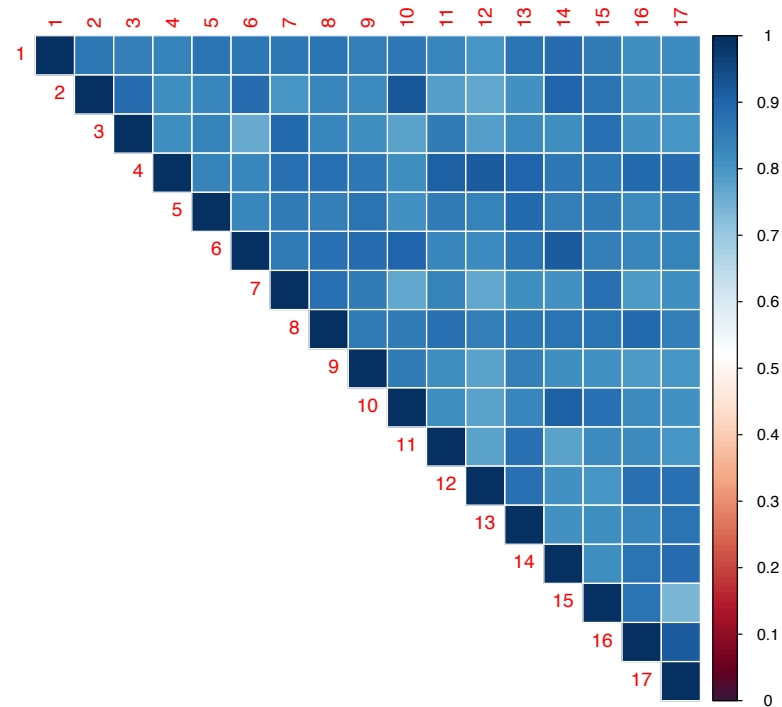


Surface based ST

Shape ST vs Image ST correlation

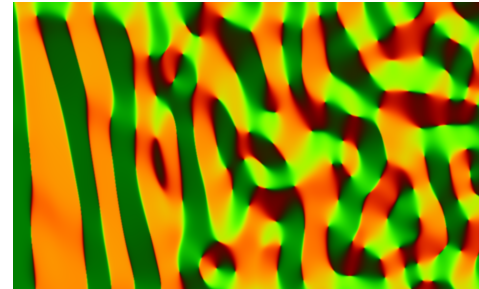


Direction

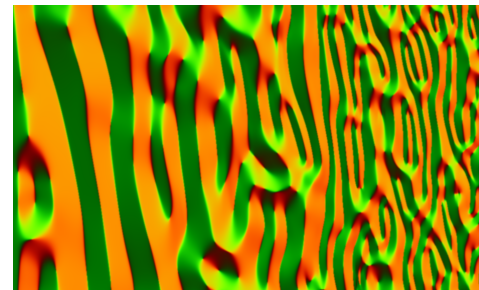


Max eigen value

Scale selection



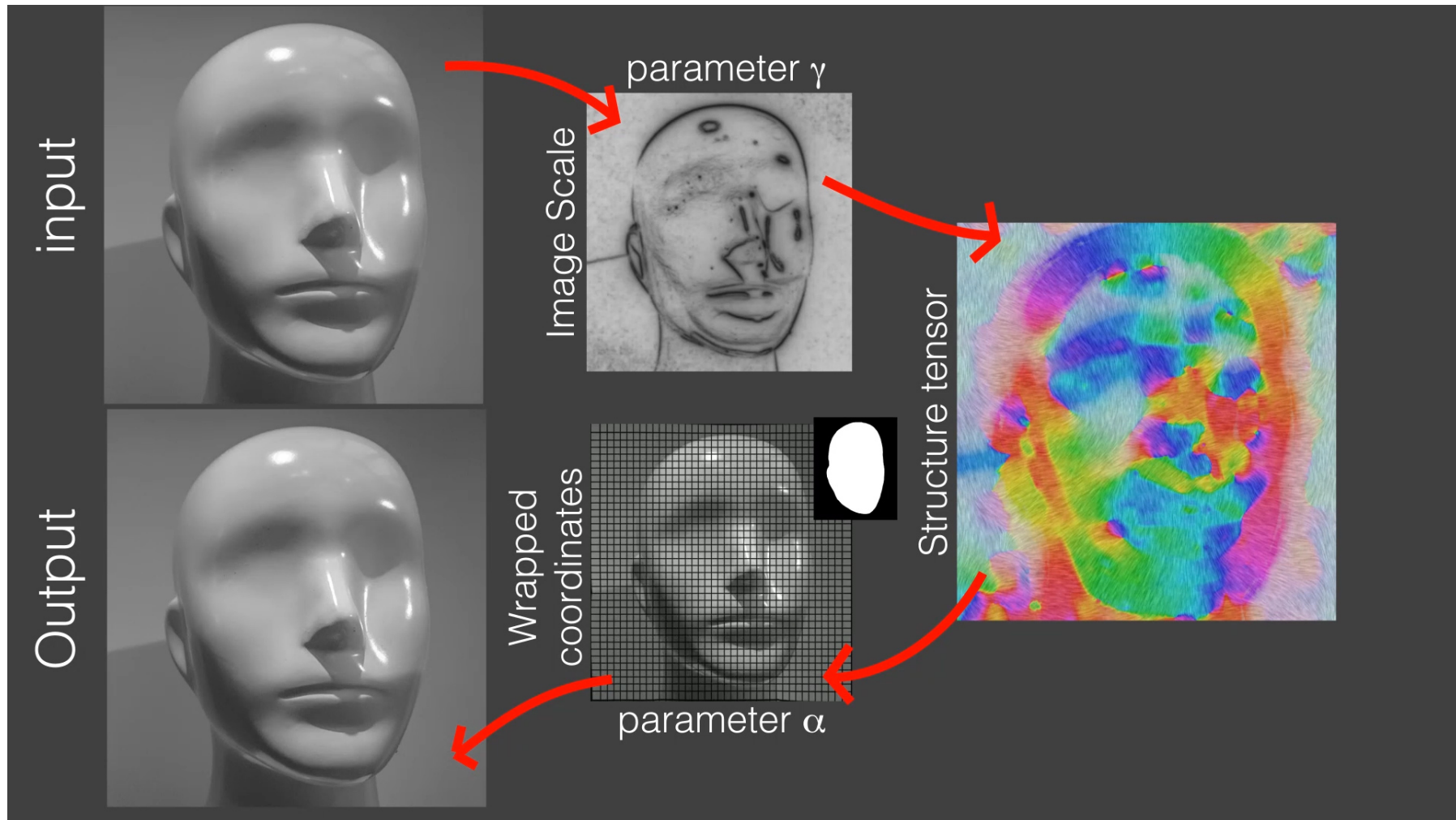
Uniform



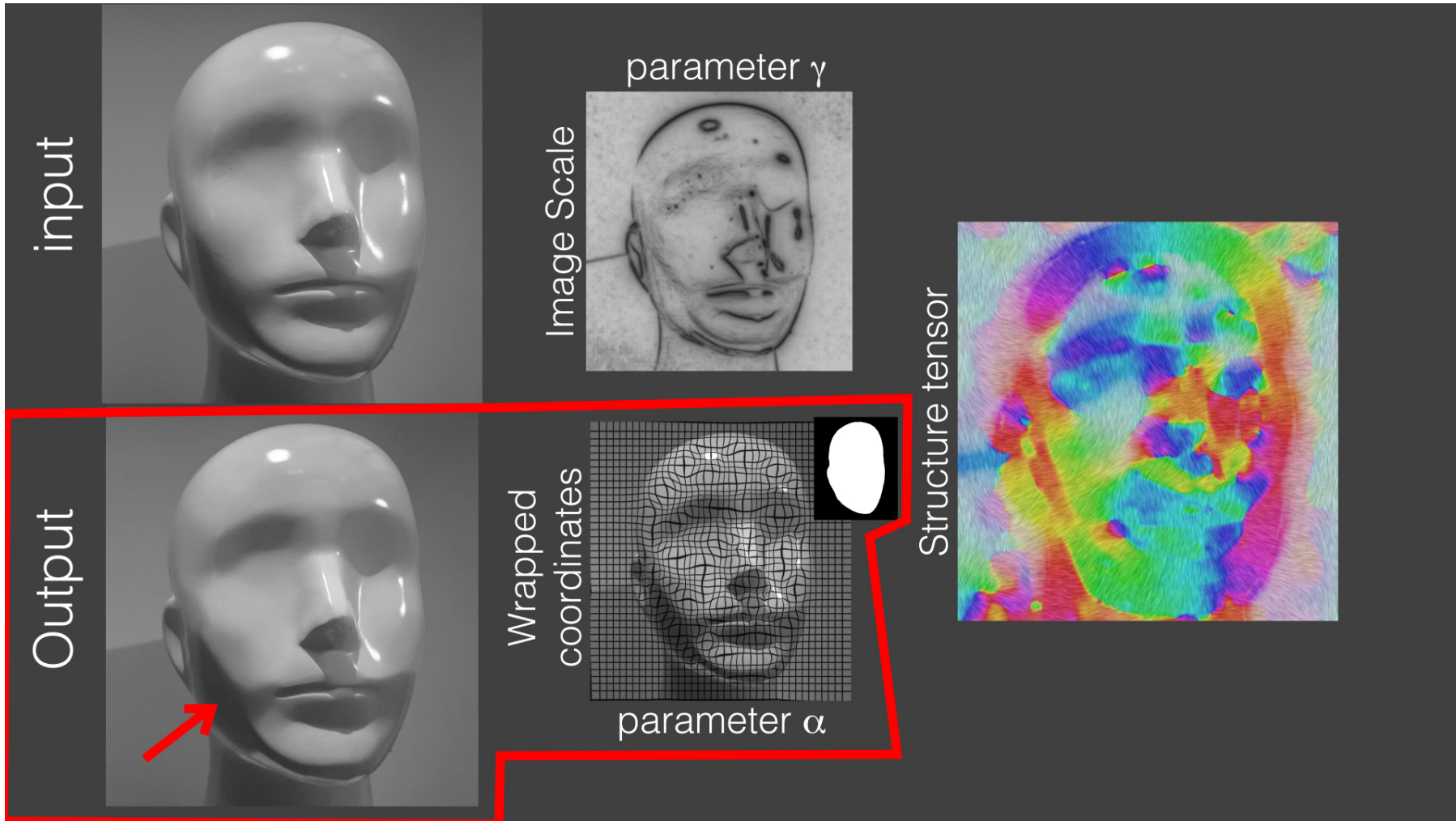
Local

$$\sigma_I(\mathbf{p}, \gamma) = \frac{\int \sigma^{2\gamma} \beta_I(\mathbf{p}, \sigma) d\sigma}{\int \beta_I(\mathbf{p}, \sigma) d\sigma}$$

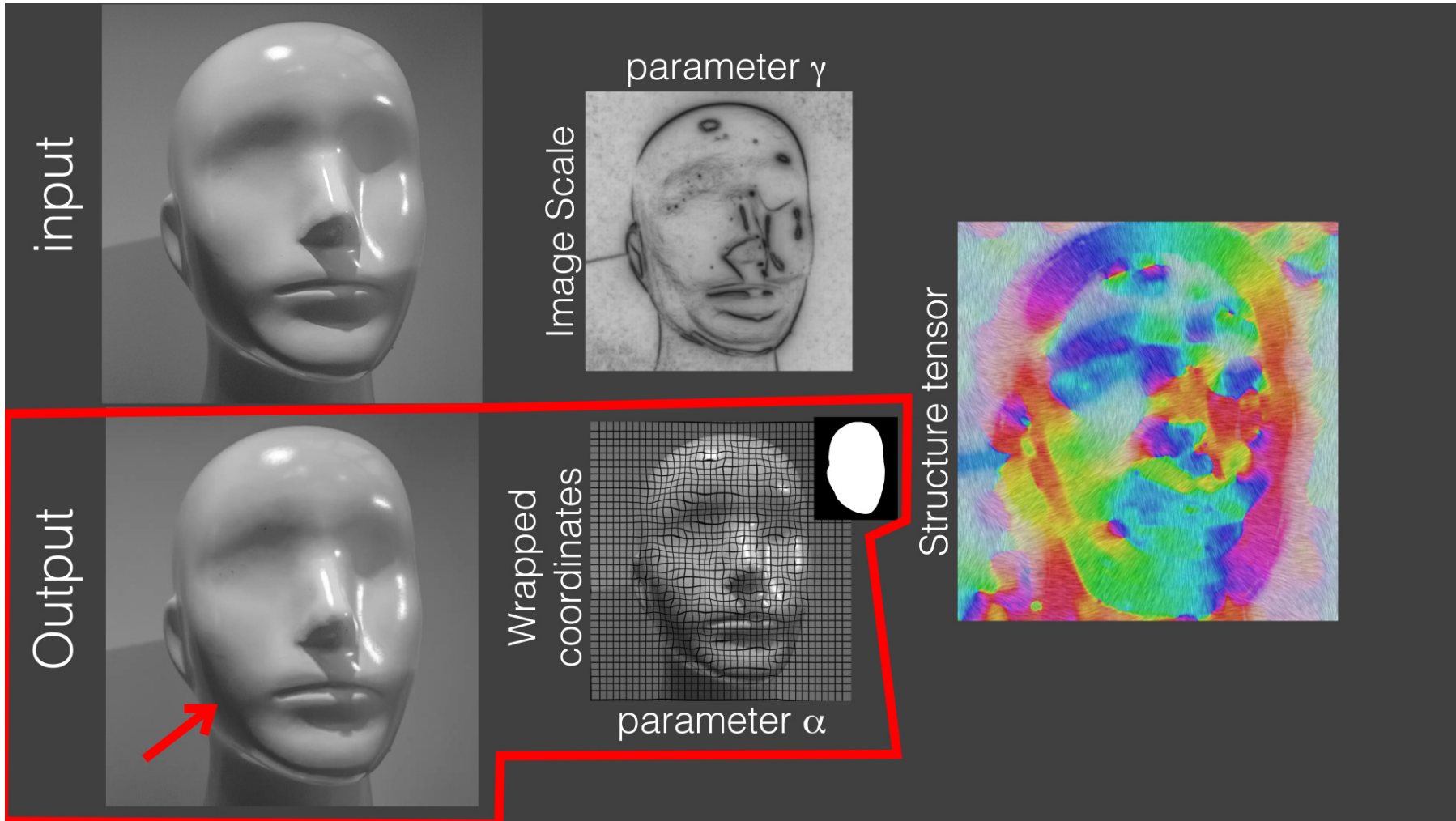
Warping pipeline



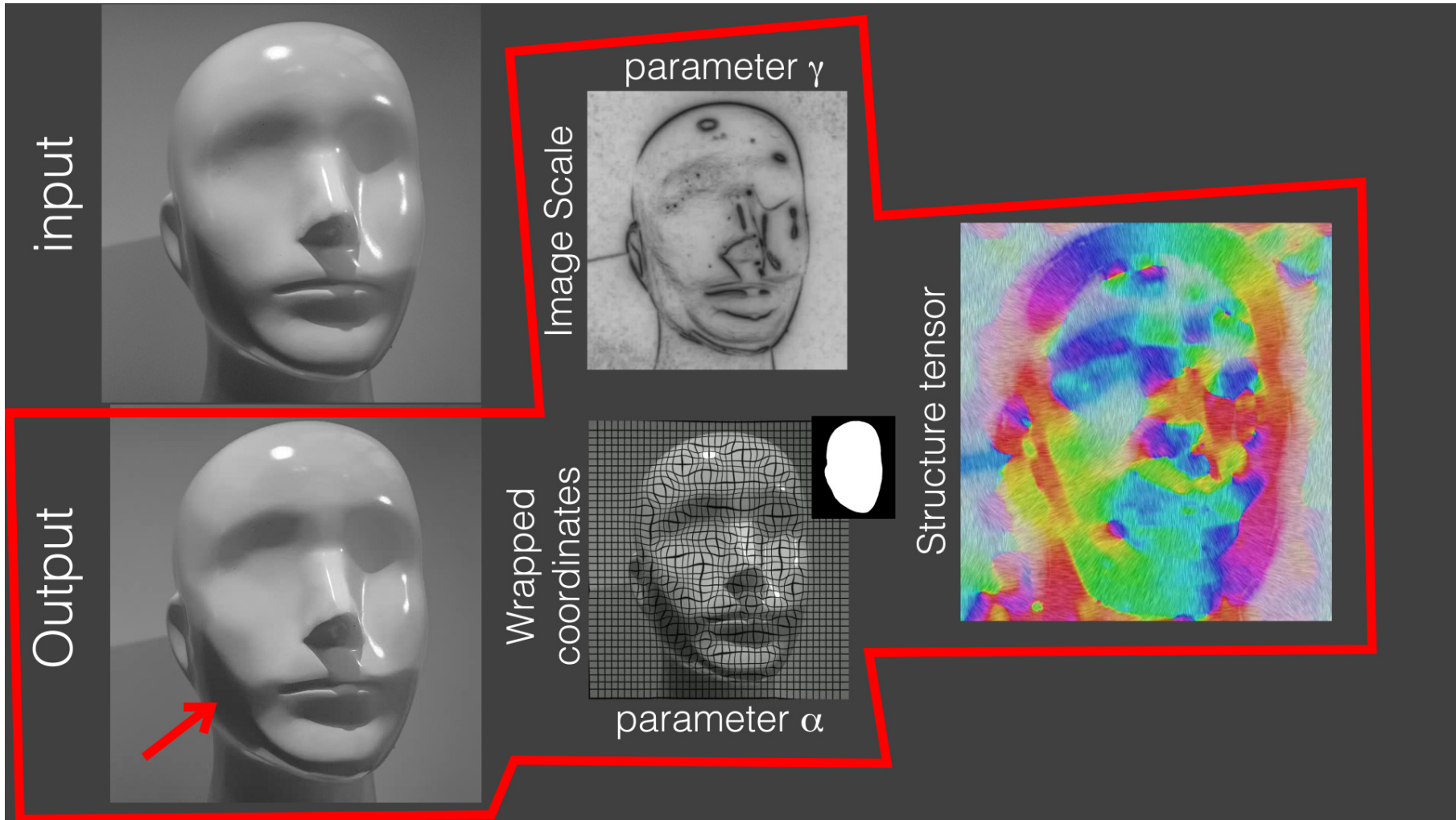
Sharpening: $\alpha = -1$



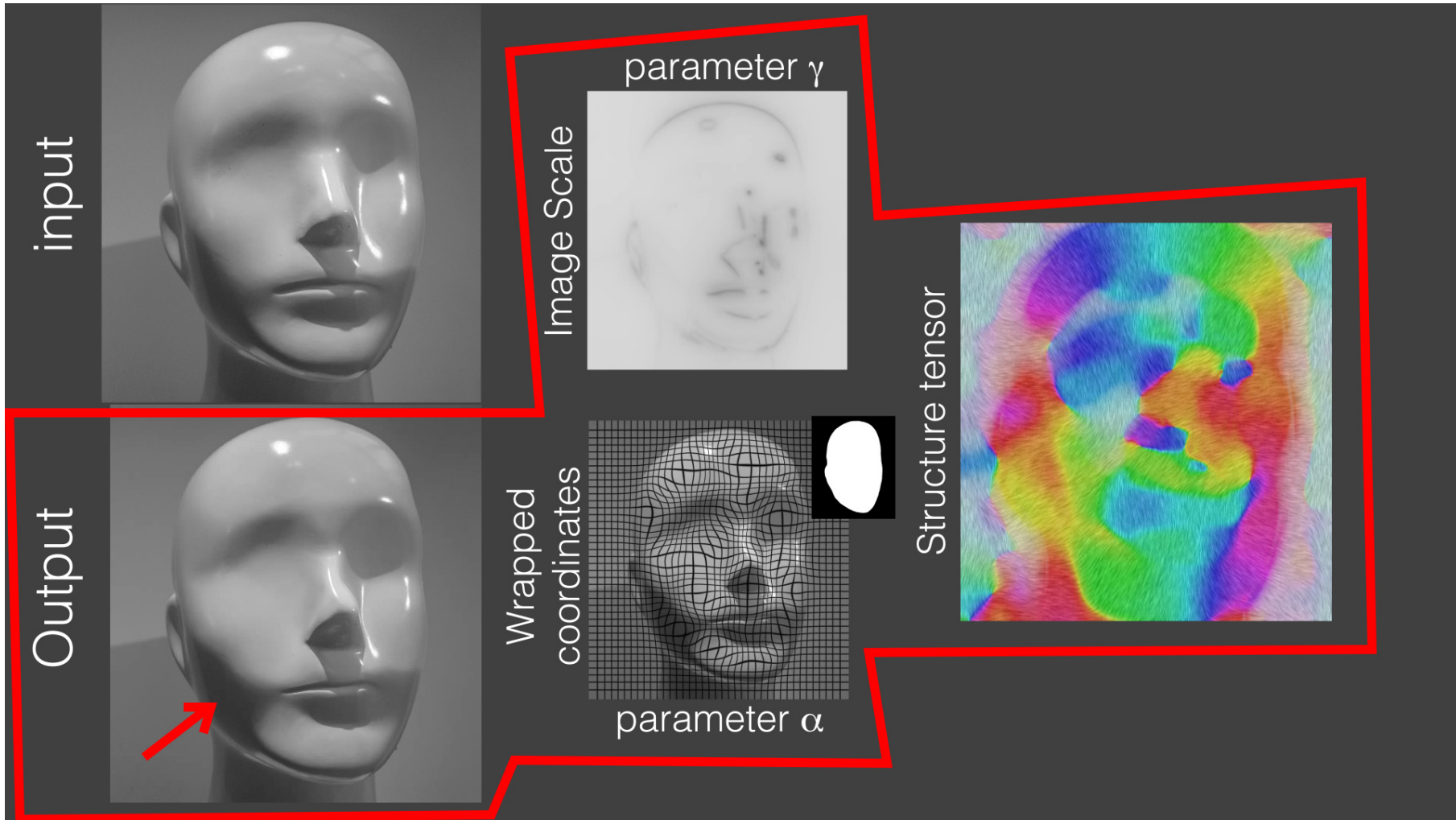
Rounding: $\alpha = 1$



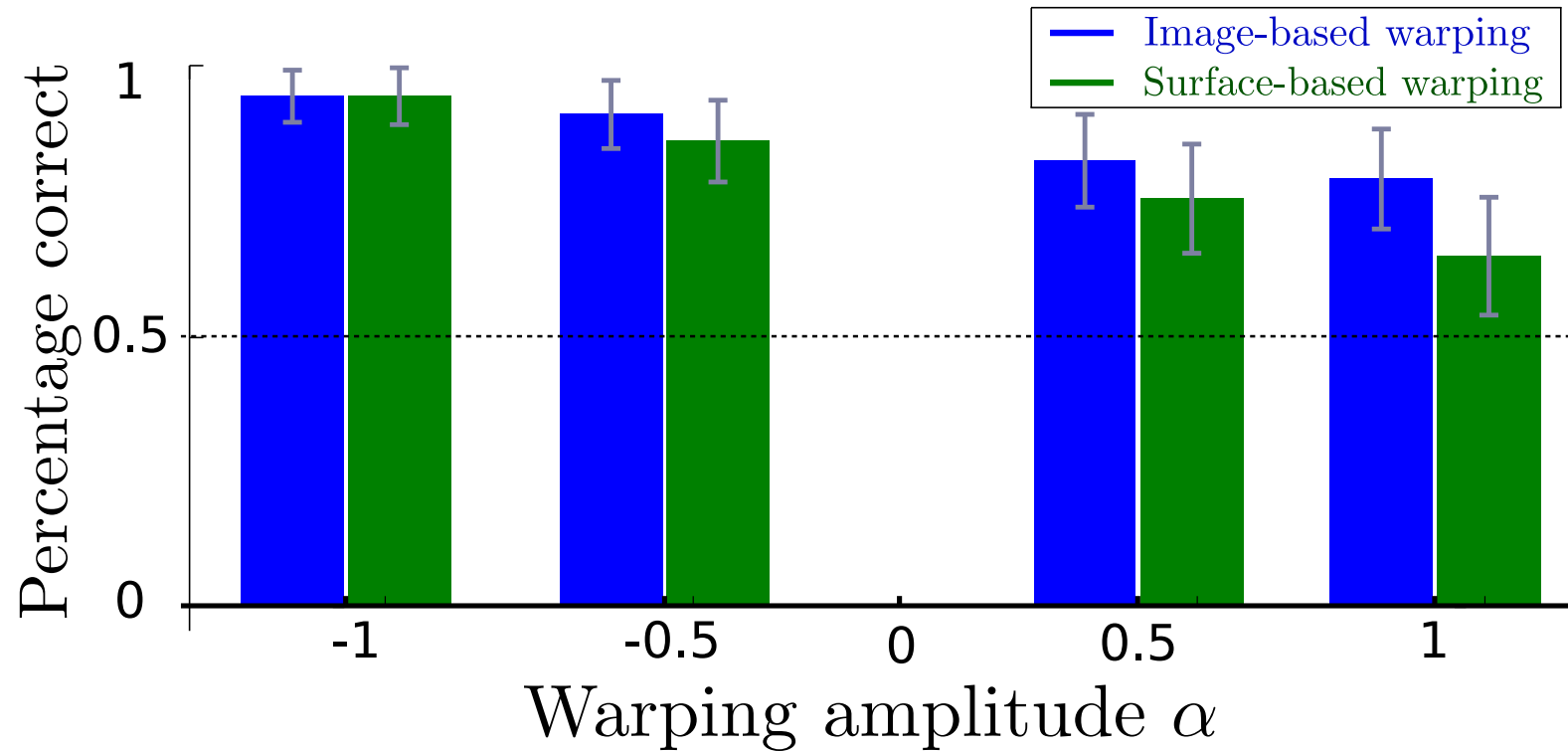
Sharpening, small scale



Sharpening, large scale



User study



Results

Conclusion

Perception issues in Visualization

Perception of Depth – Application to DVR evaluation

Perception of Noise – Application to Uncertainty Vis.

Perception of Shape – Application to Image manipulation

In this talk: low level visual perception issues

cognitive levels much more difficult

Take away message: perception matters!

