









TANGO Device Server

OSManager User's Guide

OSManager Class

Revision: - Author: taurel Implemented in C++

Introduction:

DeviceServer used to remotely access the operating system through TANGO.

Class Inheritance:

Tango::Device_4ImplOSManager

Properties:

There is no Class properties. There is no Device Properties.

Attributes:

Scalar Attributes					
Attribute name	Data Type	R/W Type	Expert		
upTime	DEV_STRING	READ	No		
time: gives the date of the day, and the current CPU hour.	DEV_STRING	READ	No		
secondSince1970: gives the number of seconds elapsed since 1970	DEV_LONG	READ	No		
cpuLoad: The cpu usage in percent.	DEV_SHORT	READ	No		
memoryTotal: Total physical memory (kB).	DEV_LONG	READ	No		
memoryFree: Physical memory available (kB)	DEV_LONG	READ	No		
swapUsed: Swap used in percent.	DEV_DOUBLE	READ	No		

Spectrum Attributes					
Attribute name	Data Type	X Data Length	Expert		
servicesList: Show all services stopped or running on this machine	DEV_STRING	1024	No		
processesList: Show all processes running on this machine	DEV_STRING	1024	No		
doubledProcessesList: List of doubled processes if any.	DEV_STRING	1024	No		

Commands:

More Details on commands....

Device Commands for Operator Level				
Command name	Argument In	Argument Out		
Init	DEV_VOID	DEV_VOID		
State	DEV_VOID	DEV_STATE		
Status	DEV_VOID	CONST_DEV_STRING		
ImmediateShutdown	DEV_VOID	DEV_VOID		
DifferedShutdown	DEV_SHORT	DEV_VOID		
ShutdownAndPowerOff	DEV_VOID	DEV_VOID		
ShellExe	DEVVAR_STRINGARRAY	DEV_VOID		
Reboot	DEV_VOID	DEV_VOID		
KillProcessByPID	DEV_ULONG	DEV_VOID		
KillServiceByName	DEV_STRING	DEV_VOID		
StartService	DEV_STRING	DEV_VOID		
ReStartService	DEV_STRING	DEV_VOID		
ReStartStarterService	DEV_VOID	DEV_VOID		
ReStartNTPDaemon	DEV_VOID	DEV_VOID		
GetOSVersion	DEV_VOID	DEV_STRING		

1 - Init

• **Description:** This commands re-initialise a device keeping the same network connection. After an Init command executed on a device, it is not necessary for client to re-connect to the device. This command first calls the device *delete_device()* method and then execute its *init_device()* method. For C++ device server, all the memory allocated in the *nit_device()* method must be freed in the *delete_device()* method.

The language device desctructor automatically calls the *delete_device()* method.

• Argin:

DEV_VOID : none.

• Argout:

DEV_VOID : none.

• Command allowed for:

2 - State

- **Description:** This command gets the device state (stored in its *device_state* data member) and returns it to the caller.
- Argin:

DEV_VOID: none.

• Argout:

DEV_STATE: State Code

• Command allowed for:

3 - Status

- **Description:** This command gets the device status (stored in its *device_status* data member) and returns it to the caller.
- Argin:

DEV_VOID: none.

• Argout:

CONST_DEV_STRING: Status description

• Command allowed for:

4 - ImmediateShutdown

- **Description:** Initiates an immediate shutdown of the operating system As this is not possible to get a remote indication of the real state of shutdown, , you should wait a few seconds before turning power off the crate, so that you let the system gracefully shutdown
- Argin:

 $DEV_VOID:$

• Argout:

DEV VOID:

• Command allowed for:

5 - DifferedShutdown

- **Description:** Initiates a shutdown after the number of seconds given as argument You should wait a few seconds before turning power off the crate to let the system gracefully shutdown
- Argin:

DEV_SHORT : number of seconds before shutdown
• Argout: DEV_VOID:
• Command allowed for:
6 - ShutdownAndPowerOff
• Description: Does an immediate shutdown and switch power off if possible Of course, the system must support the power-off feature.
• Argin: DEV_VOID:
• Argout: DEV_VOID :
• Command allowed for:
7 - ShellExe
• Description: execute a shell script with arguments as this: "cmd", "arg1 arg2" For Linux, you can add the '&' character to avoid CORBA timeout!
• Argin: DEVVAR_STRINGARRAY : path to the shell script,argument1, argument2,]
• Argout: DEV_VOID:
• Command allowed for:
8 - Reboot
• Description: Reboot system
• Argin: DEV_VOID:
• Argout: DEV_VOID:
• Command allowed for:

9 - KillProcessByPID

- **Description:** Kill a process identified by its pID.
- Argin:

DEV_ULONG: process ID

• Argout:

DEV_VOID: no argout

• Command allowed for:

10 - KillServiceByName

- **Description:** Kill a service identified by its name.
- Argin:

DEV_STRING: Name of the service to kill

• Argout:

DEV_VOID: no argout

• Command allowed for:

11 - StartService

- **Description:** Start the specified service
- Argin:

DEV_STRING: name of the service to start

• Argout:

DEV_VOID: no argout

• Command allowed for:

12 - ReStartService

- **Description:** Stop and start the specified service
- Argin:

DEV_STRING: name of the service to restart

• Argout:

DEV_VOID: no argout

Command allowed for:

13 - ReStartStarterService

• **Description:** ReStart the local starter service

• Argin:

DEV_VOID: no argin

• Argout:

DEV_VOID: no argout

• Command allowed for:

14 - ReStartNTPDaemon

• **Description:** ReStarts the NTP Daemon service

• Argin:

DEV_VOID: no argin

• Argout:

DEV_VOID: no argout

• Command allowed for:

15 - GetOSVersion

• **Description:** Returns the OS version on which the device is running

• Argin:

DEV_VOID: no argin

• Argout:

DEV_STRING: OS version

• Command allowed for:

TANGO is an open source project hosted by :



Core and Tools: CVS repository on tango-cs project Device Servers: CVS repository on tango-ds project