









TANGO Device Server

# Tango Device Server User's Guide

# **SimpleScan Class**

Revision: release\_0\_9\_4 - Author: abeilleg Implemented in Java

## **Introduction:**

Publisher is simple device which allows to publish data on the Tango bus.

## **Class Inheritance:**

- fr.esrf.TangoDs.Device\_2ImplSimpleScan
- **Properties:**

There is no Class properties. There is no Device Properties.

# **Attributes:**

Scalar Attributes				
Attribute name	Data Type	R/W Type	Expert	
configuration: current configuration	DEV_STRING	READ_WRITE	No	
CurrentScanServer	DEV_STRING	READ	No	
NbActuators	DEV_LONG	READ	No	
NbActuators2	DEV_LONG	READ	No	

Spectrum Attributes					
Attribute name	Data Type	X Data Length	Expert		
configurationList	DEV_STRING	255	No		
FromList	DEV_DOUBLE	1000	No		
ToList	DEV_DOUBLE	1000	No		
DeltaList	DEV_DOUBLE	1000	No		
FromList2	DEV_DOUBLE	1000	No		
ToList2	DEV_DOUBLE	1000	No		
DeltaList2	DEV_DOUBLE	1000	No		

# **Commands:**

More Details on commands....

Device Commands for Operator Level				
Command name	Argument In	Argument Out		
Init	DEV_VOID	DEV_VOID		
State	DEV_VOID	DEV_STATE		
Status	DEV_VOID	CONST_DEV_STRING		
DScan	DEV_VOID	DEV_VOID		
AScan	DEV_VOID	DEV_VOID		
Start	DEV_VOID	DEV_VOID		
UploadConfigToScanServer	DEV_VOID	DEV_VOID		

#### 1 - Init

• **Description:** This commands re-initialise a device keeping the same network connection. After an Init command executed on a device, it is not necessary for client to re-connect to the device. This command first calls the device *delete\_device()* method and then execute its *init\_device()* method. For C++ device server, all the memory allocated in the *nit\_device()* method must be freed in the *delete\_device()* method.

The language device desctructor automatically calls the *delete\_device()* method.

• Argin:

**DEV\_VOID**: none.

• Argout:

**DEV\_VOID**: none.

• Command allowed for:

#### 2 - State

- **Description:** This command gets the device state (stored in its *device\_state* data member) and returns it to the caller.
- Argin:

**DEV\_VOID**: none.

• Argout:

**DEV\_STATE**: State Code

• Command allowed for:

#### 3 - Status

•	Description: This command gets the device status (stored in its device_status data member) and
	returns it to the caller.

• Argin:

**DEV\_VOID**: none.

• Argout:

**CONST\_DEV\_STRING**: Status description

• Command allowed for:

## 4 - DScan

- **Description:** Launch with the current configuration but setting all the trajectories to relative positions.
- Argin:

DEV\_VOID:

• Argout:

**DEV\_VOID**:

• Command allowed for:

### 5 - AScan

- **Description:** Launch a scan with the current configuration but setting all the trajectories to absolute positions.
- Argin:

 $DEV_VOID:$ 

• Argout:

**DEV\_VOID**:

• Command allowed for:

## 6 - Start

- **Description:** Start a Scan with the loaded configuration without making any change in setting trajectories to absolute or relative positions..
- Argin:

 ${\bf DEV\_VOID}:$ 

- Argout: DEV\_VOID:
- Command allowed for:

# ${\bf 7-Upload Config To Scan Server}$

- **Description:** Load current configuration to the ScanServer.
- Argin: DEV\_VOID:
- Argout: DEV\_VOID:
- Command allowed for:

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